# Vicarious calibration of VNIR/SWIR bands of ASTER

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#### Introduction



- Background of ground-look calibration approaches
  - Difference between vicarious calibration and radiance validation
  - Motivation for calibration/validation
  - Overview of approaches for vicarious calibration
  - Description of reflectance-based approach
  - Test site overview
- Reflectance-based results for ASTER
  - Effects of solar irradiance models
  - Comparison with MODIS and ETM+ results
- Cross-comparison data
- Conclusions



### Vicarious Calibration



Vicarious calibration is a radiometric calibration approach that does not rely on sensor-based devices

- The goal is to determine the relationship between incident spectral radiance and the sensor output
  - Independent of on-board calibrators (solar diffusers and lamps, for example) and pre-flight calibration
  - Deep space looks, lunar-based calibrations
- Radiance validation is similar but it assumes that the calibration is already known
  - Preflight or onboard calibration gives the radiometric calibration and thus reported sensor radiance
  - Independent method predicts radiance at the sensor
  - If the predicted radiance matches the sensor radiance to within the uncertainties of the two methods, the sensor radiance is validated



### Why bother with vicarious?



Radiance validation is most critical for the accurate retrieval of geophysical parameters from temporal data sets with little to no overlap

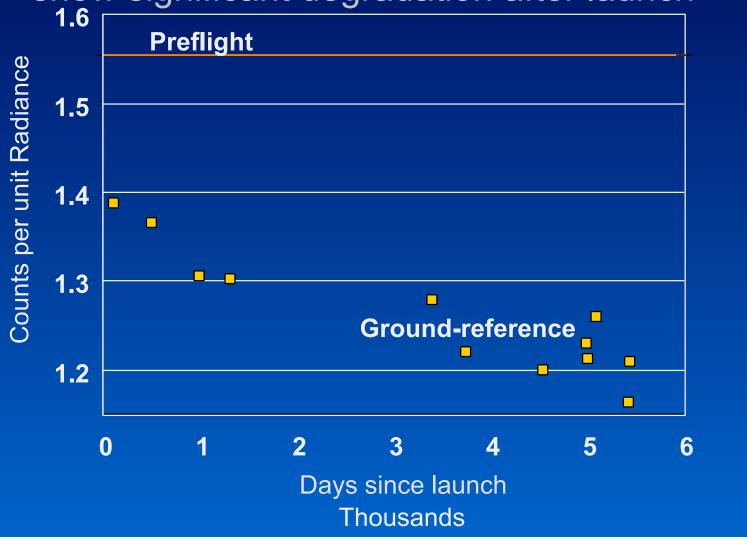
- Realistically, absolute radiometric calibration may not be needed for some specific cases
  - Data from a single sensor with focus on change analysis
  - Multiple sensors for which significant overlap exists
- Temporal studies and inter-sensor measurements, however, critically require validated sensors
  - Biases between sensors need to be removed
  - Temporal changes in response must be tracked
- Temporal studies using multiple sensors with little to no overlap in data MUST have accurate absolute radiometric calibration



### Why bother with vicarious?



Landsat-5 Thematic Mapper results from band 1 show significant degradation after launch





### Vicarious approaches



## Current approaches for vicarious calibration included terrestrial and extra-terrestrial targets

- Stellar targets have been attempted with mixed results
- Lunar approaches have been successful for several sensors
- Deep space looks
- Ground/water/atmospheric reference approaches
  - Rayleigh/molecular scattering
  - Desert scenes
  - Melting snow fields
  - Sun glint over water
  - Cloud tops



#### **UofA Reflectance-Based**



## Remote Sensing Group at University of Arizona relies primarily on a reflectance-based approach

- Atmospheric characterization
  - Aerosol amount
  - Aerosol phase function and single scatter albedo
  - Column absorber amounts (water vapor and ozone)
- Surface reflectance
  - Measurement of a preselected area from the ground
  - Use of airborne or satellite-based sensor
- Input into a radiative transfer code to predict at-sensor radiance
- Band-averaged over sensor spectral response and compared to reported radiance from sensor



### Reflectance-Based Approach





Measured
Surface
Reflectance



Measured Atmospheric Parameters

Radiative Transfer Code

Predicted At-sensor Radiance



Average Test Site
Output from
Imagery

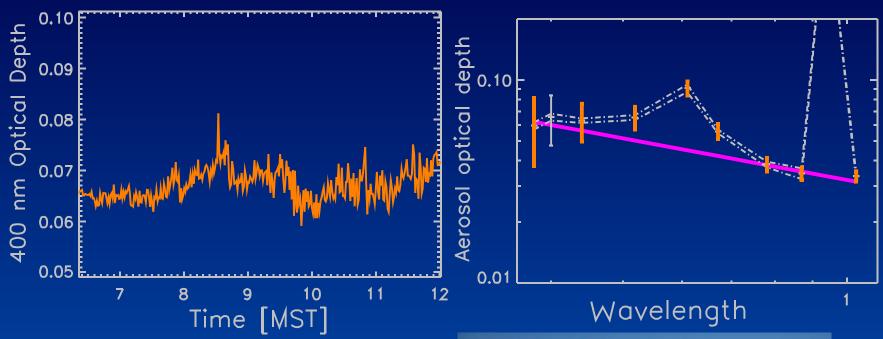
At-sensor Radiance

Evaluation of Calibration



### **Atmospheric Measurements**











### Surface reflectance



## Measure a large area of the test site related to numerous pixels of the test sensor

- Measurements of the upwelling radiance of the test site are referenced to a standard of known reflectance
- Standard is characterized in the RSG's laboratory
- Instrument is a commercially available spectrometer





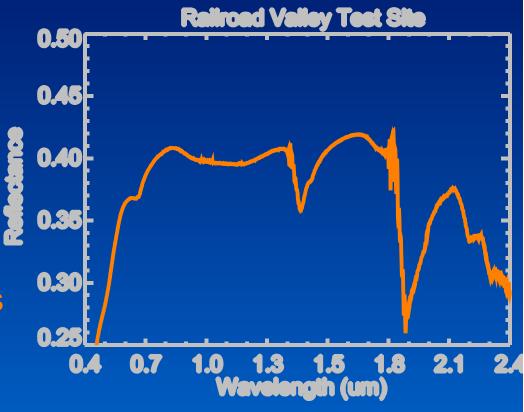


### **Surface Reflectance**



Spectral reflectance is the average of all data points collected over the entire site

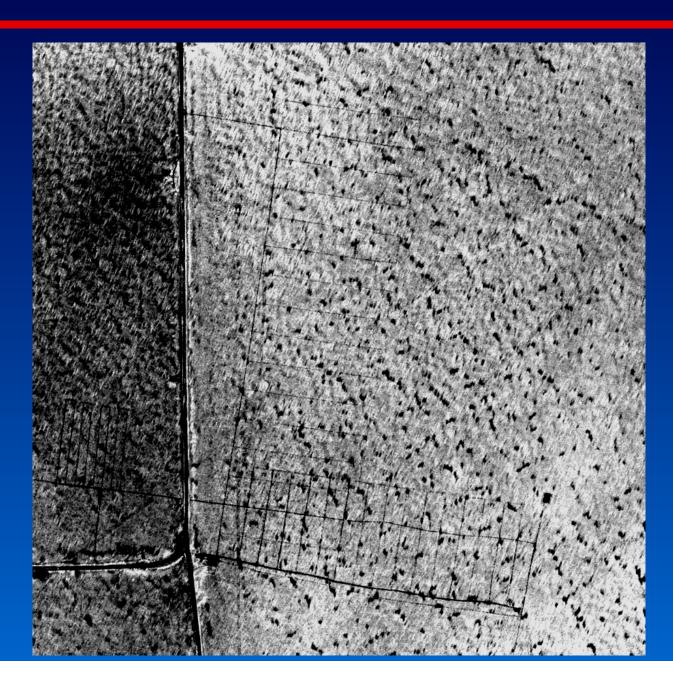
- Area covered is 300 m by 80 m
- Takes approximately 30 minutes to collect the data set
- 480 spectra that are averages of 20 samples are collected
  - 8 spectra per 20 m
  - Reflectance standards measured every 64 spectra





### **Surface reflectance**

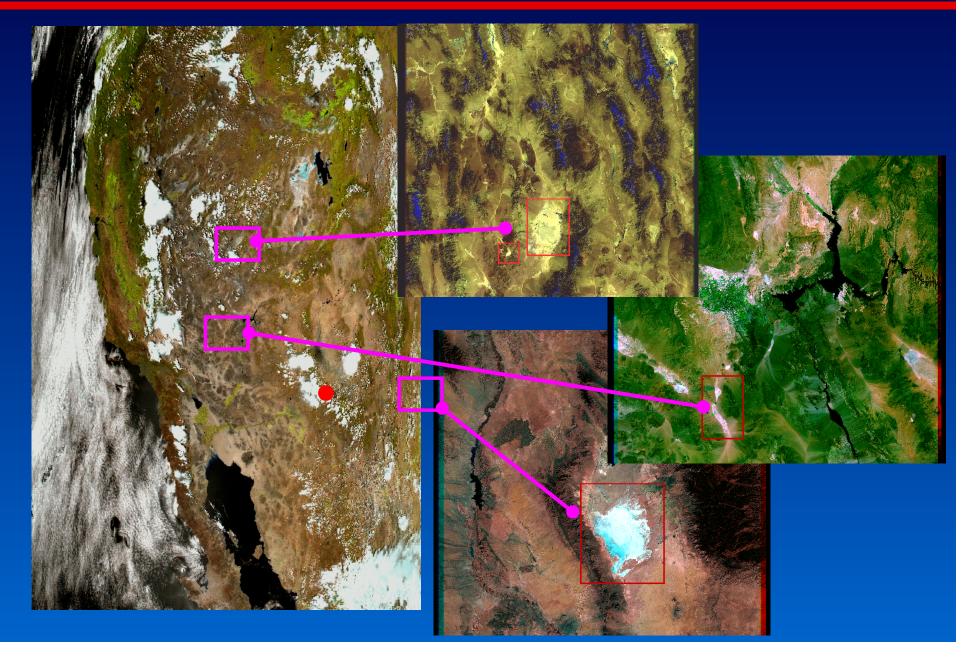






## **Test sites**

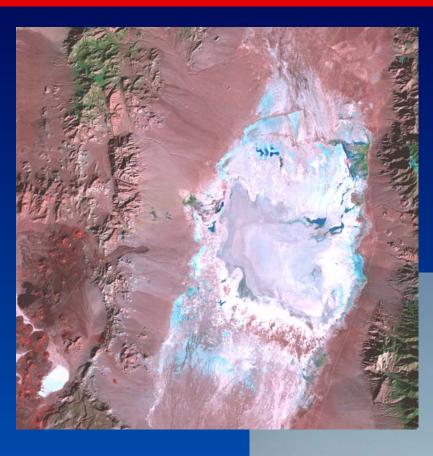






## Railroad Valley Test Site









## Ivanpah Playa test site







## **Lunar Lake test site**

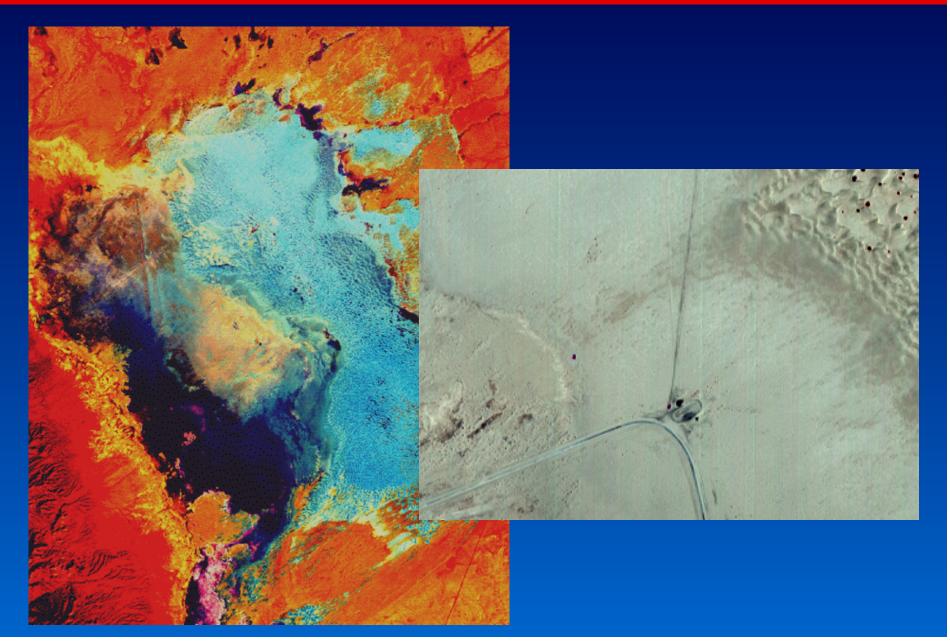






## White Sands test site







#### **Test site characteristics**



Test site selection is the most important choice in determining the uncertainties in reflectance-based approach

- Goal is to understand the interaction between the surface and the atmosphere
- Test site characteristics
  - High, flat spectral reflectance and nearly lambertian
  - Large geographic size with spatial uniformity
  - Low aerosol loading (high elevation)
  - Accessible and historical understanding of site
- Other choices such as radiative transfer code, aerosol model, instrumentation are also important
  - However, consistency of these will give good precision
  - Site selection will more dramatically impact the uncertainties and can increase the importance of the above items

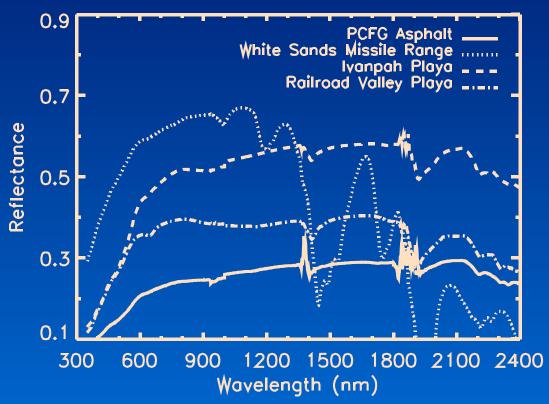


### Spectral reflectance of test sites 🔼



#### Ideal surface is flat spectrally

- Removes uncertainty due to lack of knowledge in the sensor spectral response
- Allows for a direct comparison of sensors without spectral corrections

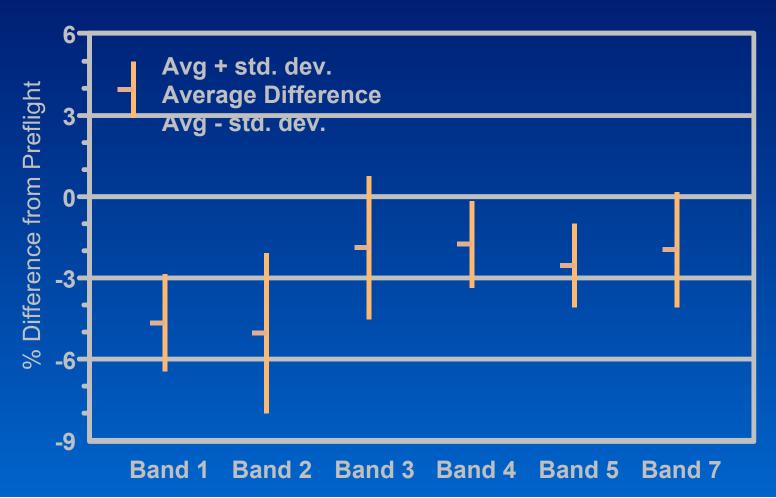




### Recent results - ETM+



Radiometric calibration of ETM+ has been shown to be stable since launch using both the radiance validation and onboard calibrators





### ASTER Reflectance-Based Results



## Evaluate ASTER calibration using both the Level 1B and the Level 1A data sets

- The comparison to the Level 1B data indicates the absolute accuracy of the radiometric calibration
  - Level 1B data have been radiometrically corrected
  - Rescaled to allow conversion to radiometric units
- Level-1A data analysis allows us to evaluate the trend of calibration
  - Determine the degradation of the sensor to better understand its radiometric properties
  - Understand how well the onboard calibrators are operating
- Level 1A data are examined using the ASTER output (counts) compared to predicted radiance from the vicarious method

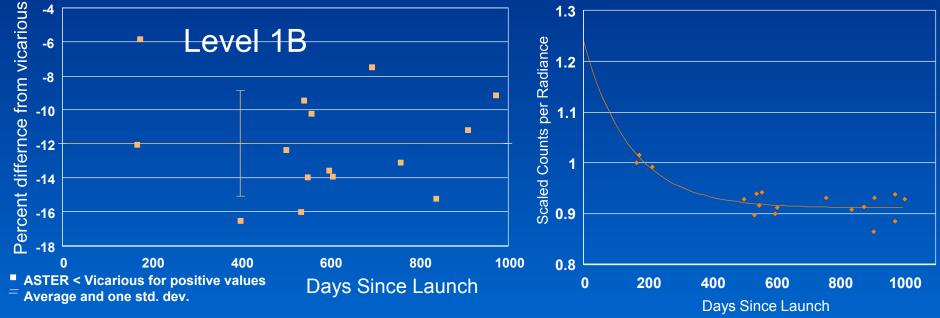


### **ASTER Band 1**



- Level 1B data do not show a strong temporal signal but do show a significant bias
- Level 1A data do show a degradation that appears to have leveled out recently



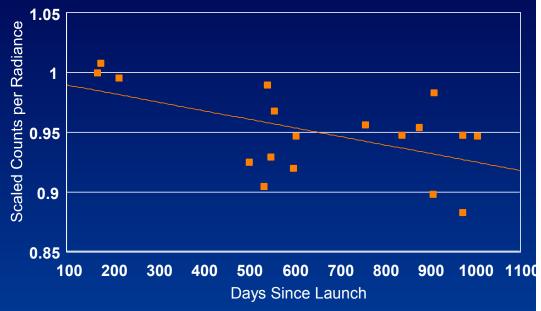


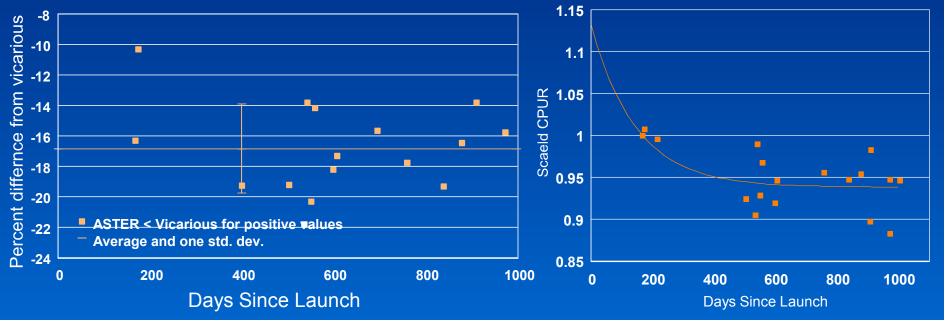


### **ASTER Band 2**



- Level 1B similar to
   Band 1 data and do not
   show a strong temporal
   signal but do show a
   significant bias
- Level 1A data do show a degradation smaller than Band 1



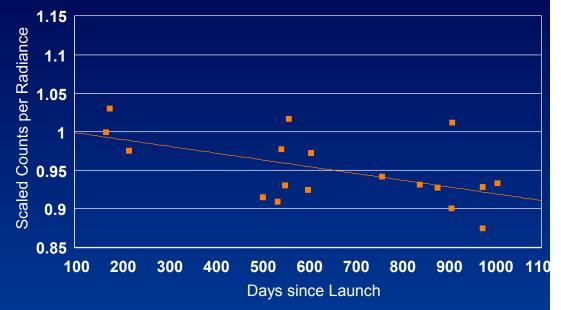


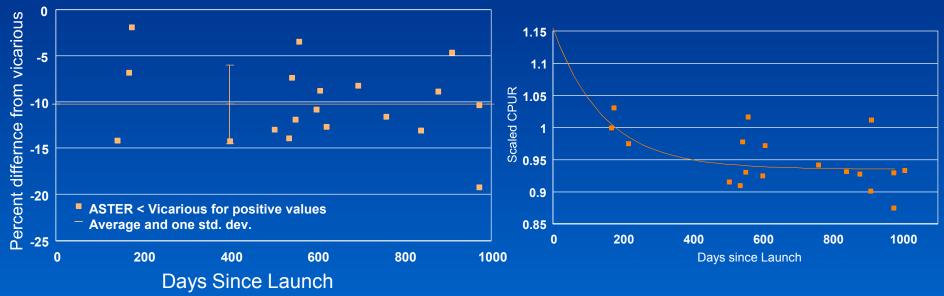


### **ASTER Band 3**



- Level 1B similar to Band 1 data and do not show a strong temporal signal but show a bias
- Level 1A data show a small degradation



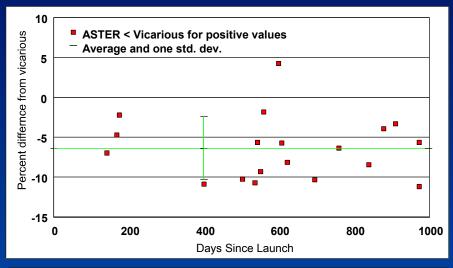


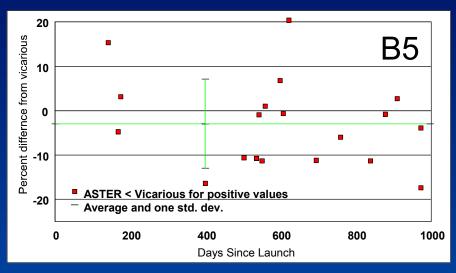


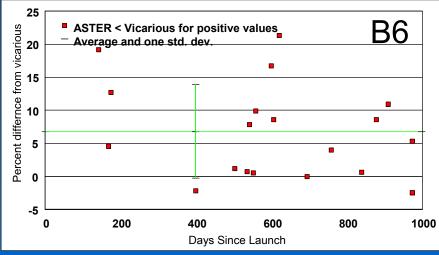
### **SWIR** bands

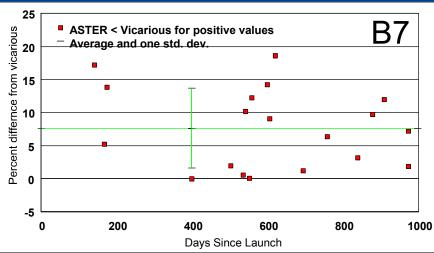


## Graphs below show Level 1B results for Bands 4, 5, 6, and 7









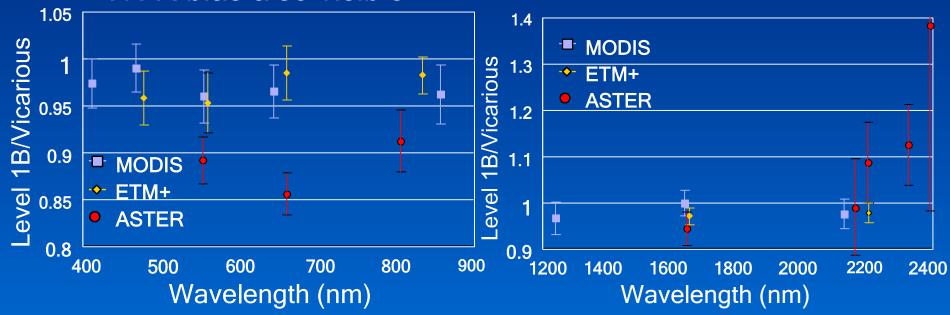


### **Summary of results**



Graphs below show the average percent difference between the vicarious results and the Level 1B radiances

- Results from ETM+ and MODIS are also shown
- Dates are not all identical
- SWIR crosstalk effect is evident
- VNIR bias also visible





### Solar irradiance model



A solar irradiance model is used to convert the radiative transfer code results to absolute radiance

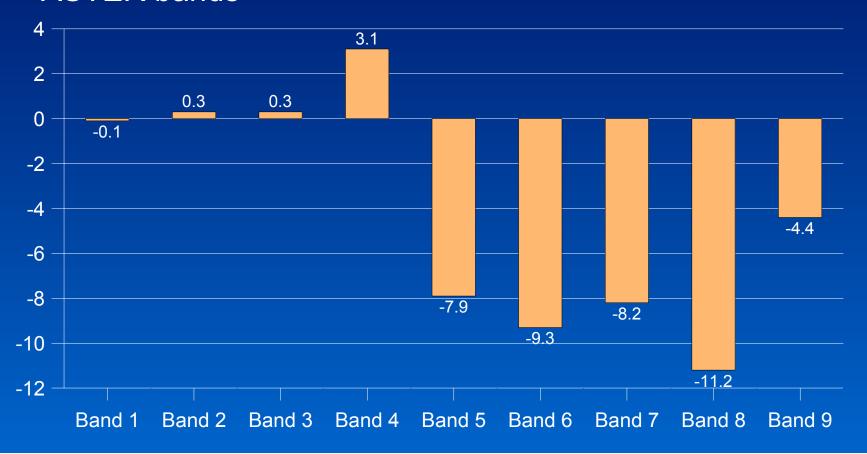
- Selection of solar model has no impact on ASTER Level
   1B radiance
  - For ETM+, ALI, MODIS, and others, the solar model is important since these sensors have solar diffusers
  - AVIRIS has "forced" the MODTRAN model to match its laboratory calibration
- The two places where the solar model impact ASTER are in the vicarious calibration and atmospheric correction
- Must have consistency between the vicarious calibration and atmospheric correction if vicarious calibration is used to adjust calibration coefficients
- Will be problems when a user decides to atmospherically correct their own data using an inconsistent solar model



### Solar irradiance model effects



- ASTER team uses a solar model called the WRC model
- Typical model used by the community is MODTRAN
- Graph below shows the % difference between the two for ASTER bands

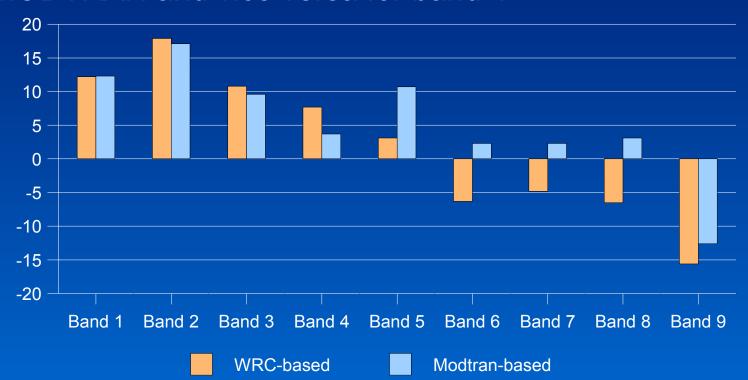




#### Effect on vicarious



- Graph shows the average percent difference between the vicarious and ASTER data
- Vicarious determined using both MODTRAN and WRC
- Bands 4 and 5 are interesting in that Band 5 is "calibrated" when considering WRC results but not MODTRAN and vice versa for band 4



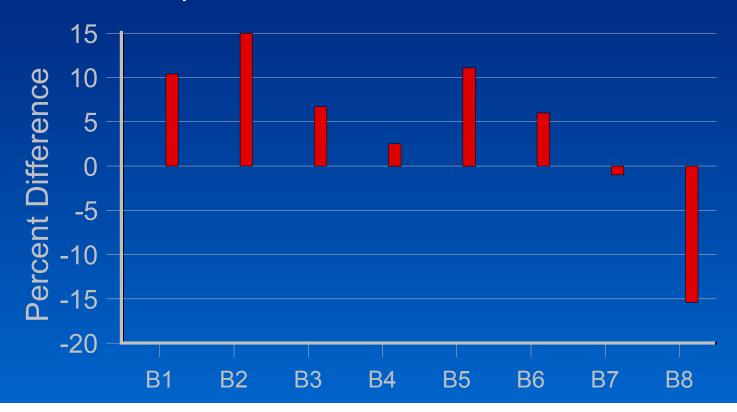


### **AVIRIS** predicting sensor radiance



Shows % difference between AVIRIS & ASTER atsensor radiances for Railroad Valley -June 30, 2001

- AVIRIS data band-averaged to ASTER spectral response
- Band 9 omitted because insufficient AVIRIS bands to cover full response of ASTER band



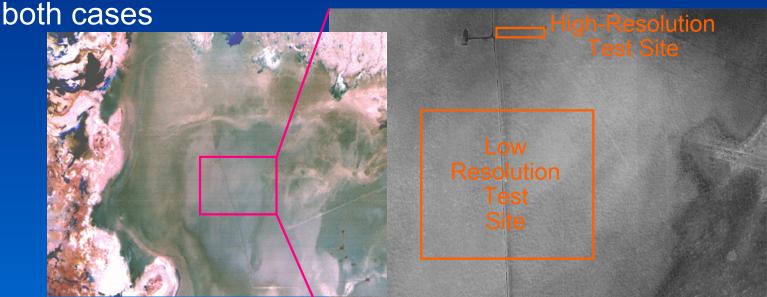


### Direct comparison results



- There exist several days of coincident ground data along with MODIS and ASTER data
- Can calibrate both sensors using the same site at RRV playa
  - 1 km² area of Railroad Valley used for both sensors
  - Same radiative transfer code inputs and results
- Dates shown here were from May 16 and June 14, 2002

Band 1 of ASTER had saturated pixels within the site in



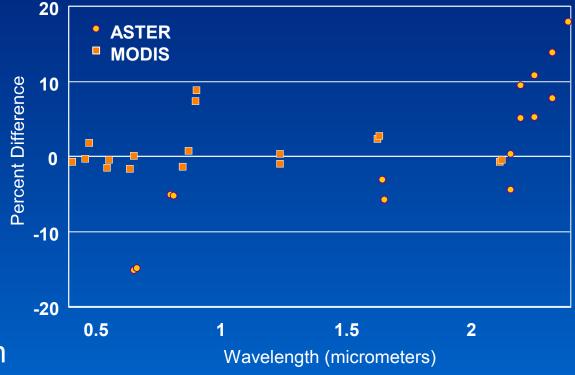


### Coincident MODIS data



## Using ASTER and MODIS data from the same site for May 16 and June 14, 2002 are shown below

- Both dates show consistent results for MODIS in all bands and for VNIR bands of ASTER
- Band 1 of ASTER was saturated on both dates
- Note the bias is still present in Band 2 and to lesser extent Band 3
- SWIR crosstalk effect also apparent
- Difference between dates in the SWIR is under investigation





### Cross-comparison in reflectance



0.6

Reported ETM+ Radiance

Interpolated Surface Reflectance

## Can also atmospherically-correct data to reflectance and then compare in reflectance

Radiance [W/(m^2

100

80

60

Radiance comparisons work when overpasses are

nearly coincident

 Other cases require a correction for atmospheric differences and geometry

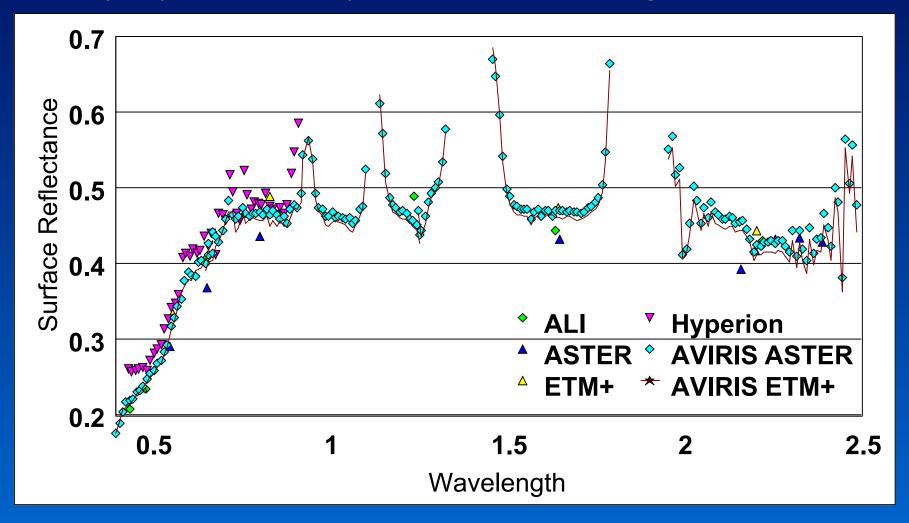
- Instead compare surface reflectance
- Atmospheric correction based on measured atmospheric conditions as input to a radiative transfer code for two representative reflectances
- Linear interpolation from a known radiance gives the surface reflectance



### **Cross-comparison results**



Summary of retrieved reflectance of Argentinian playa (El Leoncito) in Jan. 2001 for given sensors

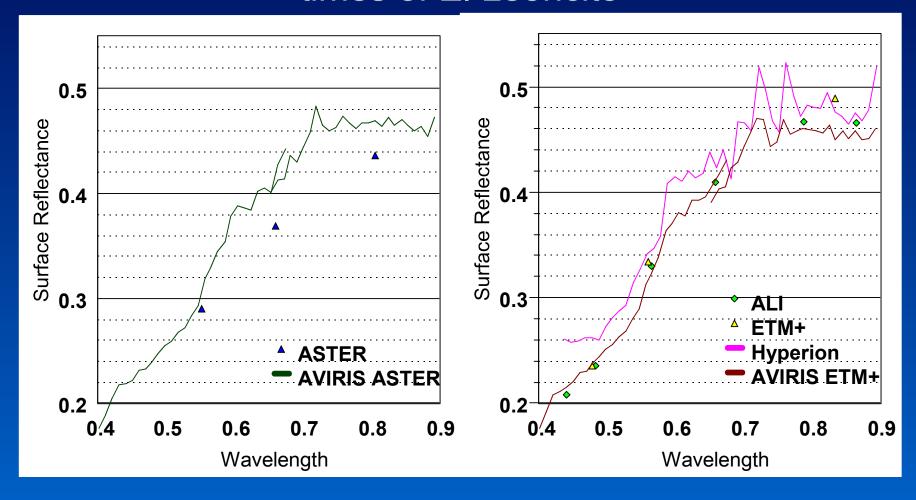




### **Cross-comparison results**



## Comparison of VNIR bands for similar overpass times of El Leoncito





### Conclusions



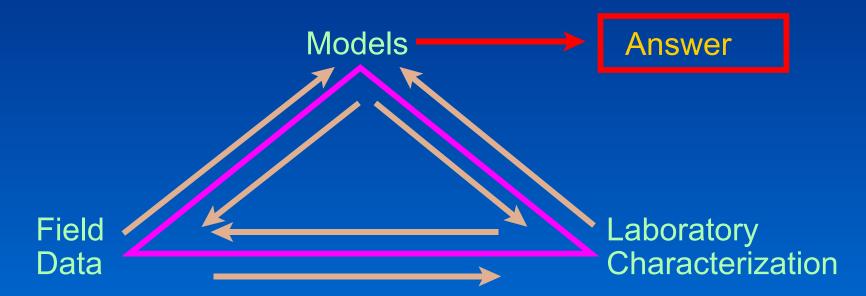
- ASTER VNIR bands
  - Bias in the Level 1B radiance
  - Level 1A results are beginning to diverge from the onboard calibrator results
  - Gaps will be filled with comparisons to MODIS
- ASTER SWIR bands
  - No strong temporal degradation
  - Crosstalk effect is large enough over vicarious sites to cause confusion in interpreting bands 5-9
  - Bands 4 and 5 could be susceptible to error when doing own atmospheric correction
- Cross-comparison to other sensors shows similar results as the reflectance-based calibrations
  - ASTER VNIR bands are not consistent with many other EOS sensors
  - SWIR data require a cross-talk correction



### Conclusions



- Reflectance-based accuracy is approaching 3% in visible and near infrared
- Precision is near 2% in the VNIR [1-σ]
- Further improvements to precision will be found by evaluating all aspects of the problem
  - Understanding of field instrumentation
  - Greater frequency of field collections
  - Evaluations of the radiative transfer codes





### Conclusions



- Current level of precision is adequate for trending if done at greater frequency
  - 12 times per year (that's successful collections)
  - Onboard systems provide better frequency and precision
- Improvement in precision allows trending with fewer collections per year
- Once precision is reduced, then it is possible to determine biases
  - Cross-comparison work gains further confidence
  - Apply approach to a greater number of data sets
- These types of data sets as well as others (lunar view, additional sites) will be critical over the next 12-24 months to evaluate the onboard calibrators and crosstalk correction software